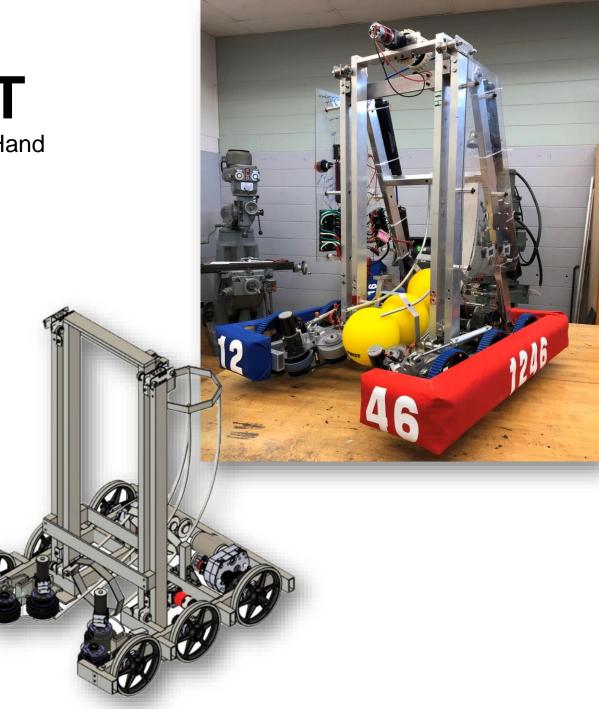
# **Projects Portfolio**

#### Ziming [Tiger] Ye Mechatronics Engineering - University of Waterloo

# FRC 2019/2020 ROBOT

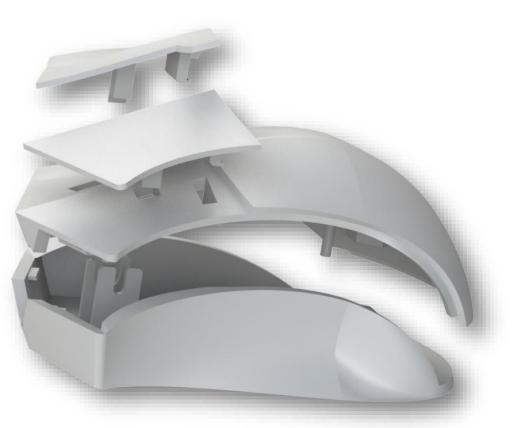
**Skills:** Fusion 360, Drill Press, Filing, Milling, Band Saw, Hand Drill, Riveting, Communication, Leadership

- Designed robot in Fusion 360 around tasks outlined by the 2020 FRC game
- Static stress simulations performed in Fusion 360 to ensure climb mechanism could support robot weight
- Integrated parts from McMaster-Carr into design of robot
- Directed workflow and communicated with other leads in a fast-paced work environment



### 3D PRINTED COMPUTER MOUSE &

**Skills:** SOLIDWORKS [surfacing tools], GD&T, Measuring Dimensions, Iterative Design, Cura





- Designed a mouse body using surfacing tools in SOLIDWORKS
- Mouse was designed for a previous circuit board so dimensions were precisely measured
- Went through iterative design testing to perfect the shape and feel of mouse

Name	Tiger Ye	Channel default	Submit
		Connected to: default	
Tiger Ye		Channel: default	
Hello V	Vorld		
someone123	}		
Hi			
I			Send

# CHAT APP 🖉

**Skills:** Node.js, jQuery, JavaScript, CSS, HTML, Ably Realtime API, Heroku, Express.js

- Programmed online chatroom application using Ably Realtime API
- Utilized Express.js for backend JavaScript code
- Applied jQuery to add HTML message components to chat
- Hosted application on Heroku servers

# COVER LETTER TEMPLATE SCRIPT &

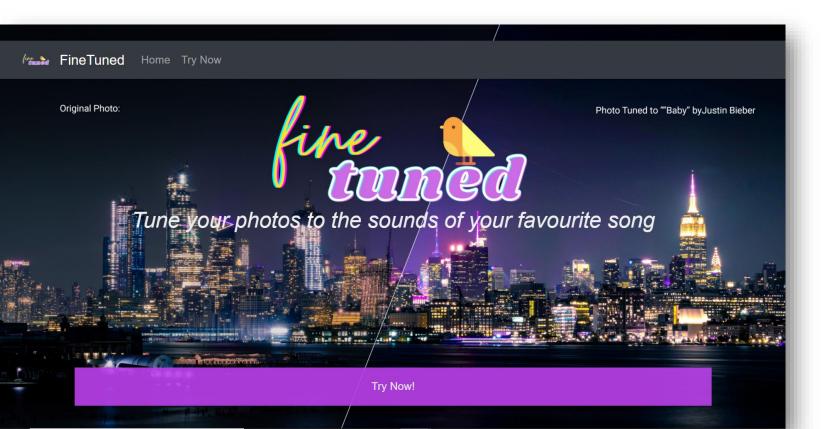
Skills: Python, Selenium, Python-docx, Xpath

Ziming [Tiger] Ye			
547-621-0076	t28ye@uwaterloo.ca		
Mar 15, 2021			
Division			
Company			
Address			
Waterloo, Ontari	o, N2L 3X2		
Dear Hiring Man	ager,		
	me of the skills I possess that would make me a great fit for eSolutions Group. I would love to answer talk more about my experiences in an interview. Thank you for your time.		
Sincerely,			
Tiger Ye			

- Programmed cover letter template script in Python
- Utilized Selenium to access employer information through WaterlooWorks and write to Word using Python-docx
- Automated the template script to go through all items in my shortlist
- Always trying to improve it every work term :)

### FINETUNED @

Skills: Python, PIL Library, Spotify API, Flask



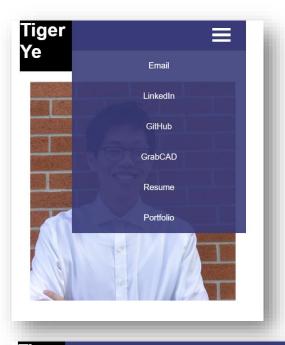
- Designed a webpage that edits photos based on song data
- Used PIL Library in Python to edit images based on Spotify API values
- Utilized Flask to build parts of application using Python

## CONVEYOR ASSEMBLY &

Skills: SOLIDWORKS, GrabCAD, McMaster-Carr

- Designed a modular sorting conveyor system in SOLIDWORKS
- Selected motor from McMaster-Carr taking into consideration continuous operating torque, duty cycle etc.
- Organized conveyor into multiple assemblies and sub-assemblies





# PERSONAL WEBSITE &

Skills: JavaScript, SCSS, CSS, HTML

- Created a responsive personal website using JavaScript, SCSS and HTML
- Used keyframes for subtle animations
- Utilized media screen to create an adaptive webpage perfect for all screen sizes
- Uses exec commands to unobtrusively copy email to clipboard



Tiger

#### ABOUT

Email

I inkedlr

Hi my name is Tiger Yel Currently I am an undergraduate student studying Mechatronics Engineering at the University of Waterloo. My passion is in CAD work, however I love to branch out occasionally into other fields such as programming and circuit design.

GitHub

GrabCAD

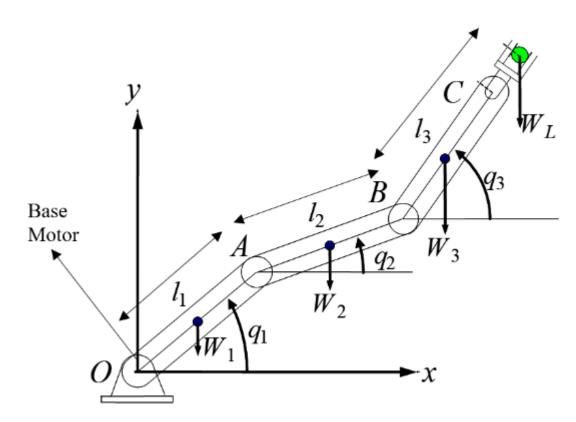
Resume

Portfolio

At this very moment I am in my 2A term in Mechatronics and looking for work during for the winter term. I hope that you will consider me for your company!

# LEAST TORQUE CALCULATOR $\mathscr{O}$

Skills: C++, Cosine Law, Vectors



- Designed and programmed a C++ script to find the combination of 3 links that produce the least torque in 3 positions
- Utilized Cosine Law to find the length of the first
  2 links
- Implemented link collision detection to detect if links are intersecting
- For a detailed look check out this <u>report</u>!

	Gripper Location	Link 3 Orientation
Position 1	x = 0.75m, y = 0.1m	$q_3 = -60^\circ$ w.r.t the x-axis
Position 2	x = 0.5m, y = 0.5m	$q_3 = 0^\circ$ w.r.t the x-axis
Position 3	x = 0.2m, y = 0.6m	$q_3 = 45^\circ$ w.r.t the x-axis

# **Some Other Projects**

- Curling Game *2* My first big coding project, a curling game coded in Python using Pygame
- 3D Printable Turntable *∂* Designed a simple turntable for my mom to hold kitchen spices in Fusion 360
- Game of Pig *P* Programmed the game of pig in Java for a culminating project
- Phone Stand *P* Designed an adjustable phone stand in SOLIDWORKS for project
- IEEE754 Converter *2* Programmed Java application that manually converts integers to IEEE754 and vice-versa
- **Millennium Puzzle** *A*–Used Fusion 360 to design a intricate prop from a childhood TV show
- Car CAD *P* Designed a simple car using surfacing features in Fusion 360

For More Check Out My

GitHub: <u>https://github.com/tigerqye</u> ∂

GrabCAD: <a href="https://grabcad.com/tiger.ye-1">https://grabcad.com/tiger.ye-1</a>